

A Graph-Based Formal Semantics of Reactive Programming from First Principles

Bjarno Oeyen, Joeri De Koster, Wolfgang De Meuter

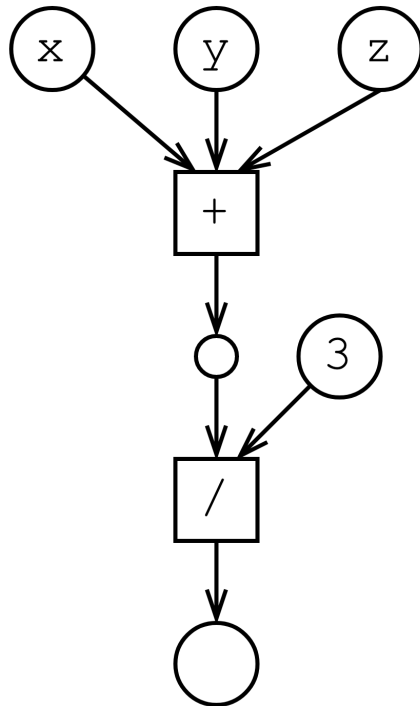
Software Languages Lab, Vrije Universiteit Brussel, Belgium

FTfJP Workshop @ Ecoop (07/06/2022)

Reactive Programming in Haai



```
(defr (average x y z)
  (/ (+ x y z) 3))
```



- Syntactically looks like Scheme code
 - Makes graphs

- **Reactive semantics**

- Instead of *applying* functions, reactors are *deployed*.
- Instances of reactors are called **deployments**

- **Push-based propagation**

- Evaluation of RP programs in **turns**.

- Haai-specific characteristics

- Everything is a reactor (even + and /)
- Higher-Order Reactors

Higher-Order

Sounds like...

Haai

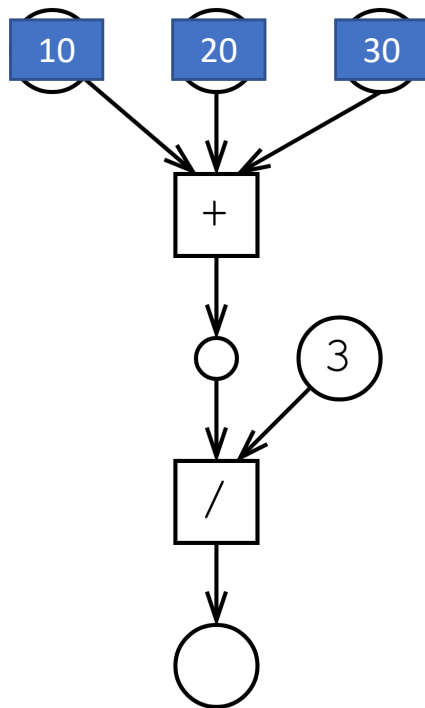
Is Dutch for...

Shark

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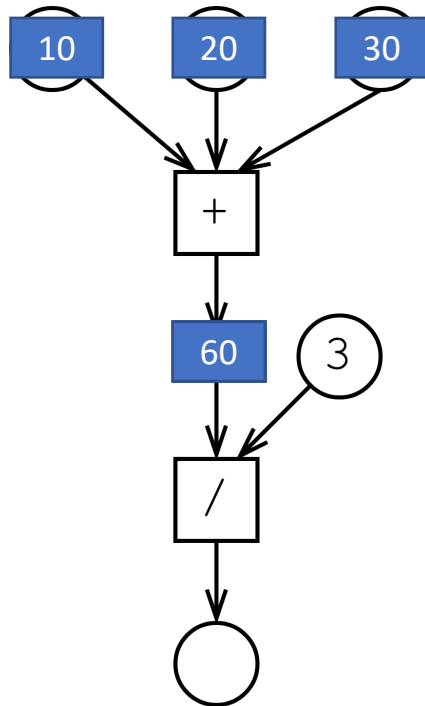
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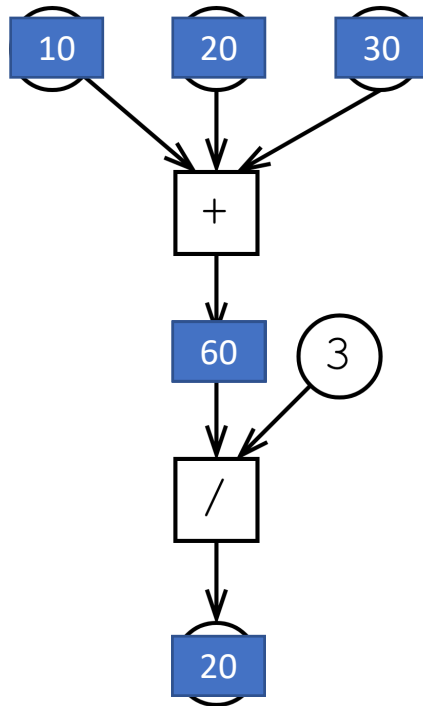
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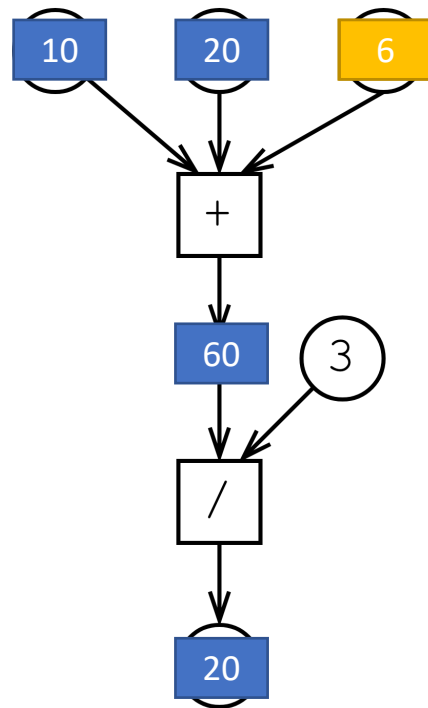
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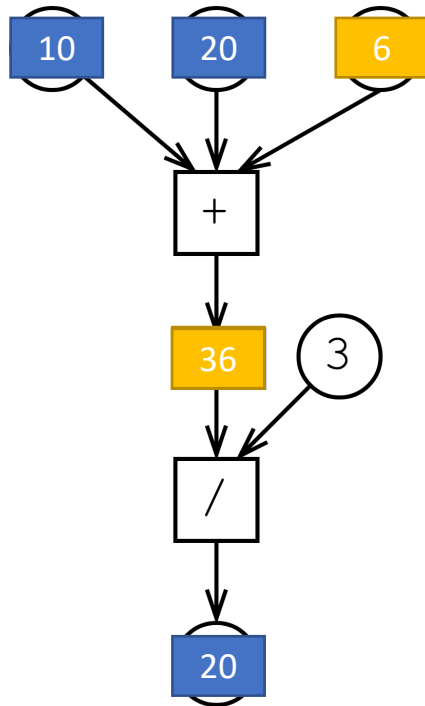
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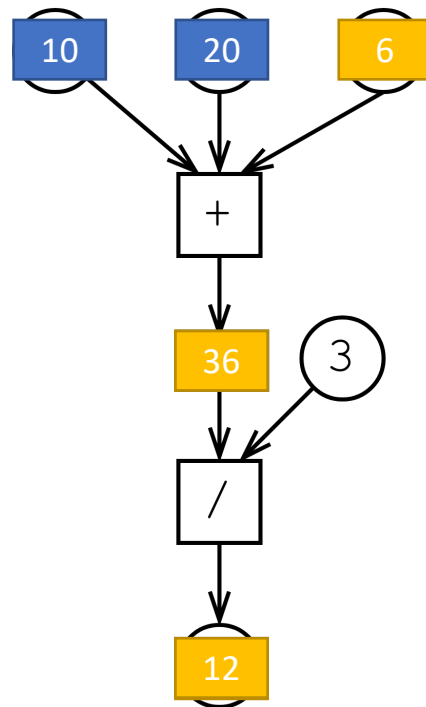
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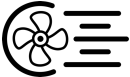
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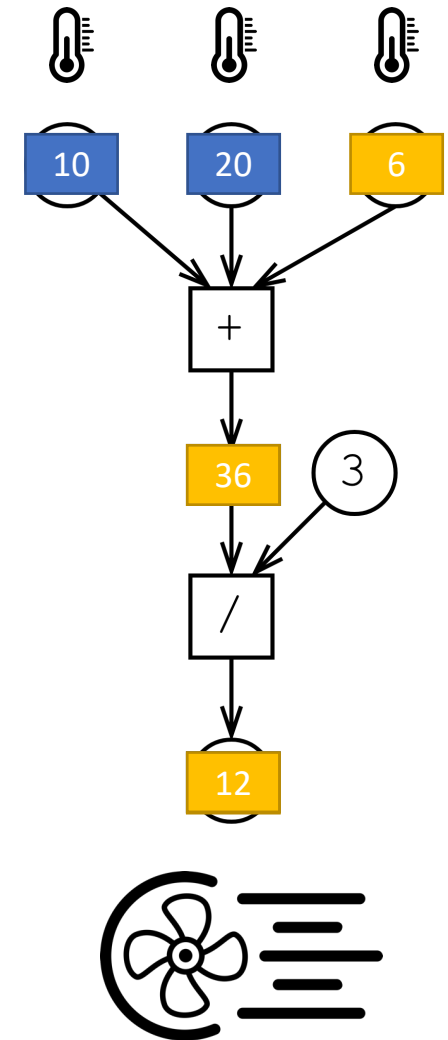
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Reactive Programming in a nutshell

- **Automatic recomputation** of program state
 - By **declaring** constraints/dependencies between *signals*
 - **No callback hell** to keep data dependencies updated
- **Sources** bound to data producers 
 - E.g., user input, sensors...
- **Sinks** bound to data consumers 
 - E.g., actuators, user interface...
- Other “RP” languages:
REScala, Frappé, FrTime, Elm, ReactiveX, Akka Streams...



- **Motivation**

- Formalisation

- Lessons learned

Two implementation styles of RP languages

- **Function-Based**

Functions & Function Composition

Examples: Fran, Yampa, SFRP, Dunai...

- Usually implemented in Haskell...

Well-studied
(\exists many formalisations of
function-based RP)

- **Graph-Based**

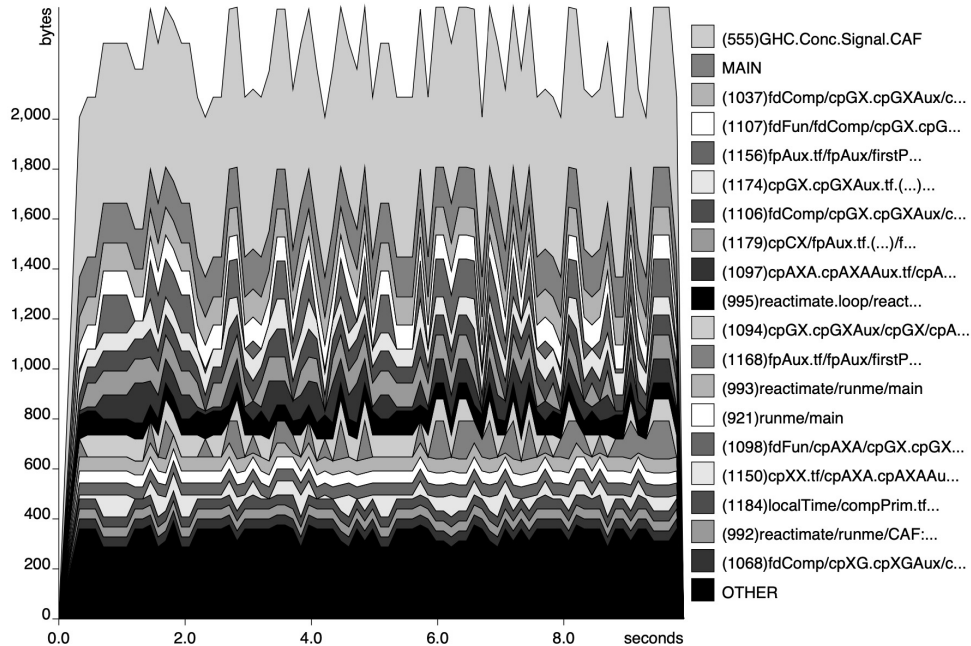
Graphs & Graph Composition

Examples: FrTime, REScala, Frappé, EmFRP...

Not as well studied as
function-based RP

So why bother
formalising graph-
based RP?

Memory Usage of a Yampa program



Memory usage of a simple Yampa program. Memory usage constantly fluctuates = GC needed.

- Haskell RP languages are, in general, unsuitable for embedded devices [*]
 - E.g., IoT, CPS, Real-Time Systems
- Risk of space leaks
- Need for a **garbage collector**
- ...
- Which is usually also the case of their formalisations.

[*] Sawada, K., & Watanabe, T. (2016, March). Emfrp: a functional reactive programming language for small-scale embedded systems. In *Companion Proceedings of the 15th International Conference on Modularity* (pp. 36-44).

- Motivation

- **Formalisation**

- Lessons learned

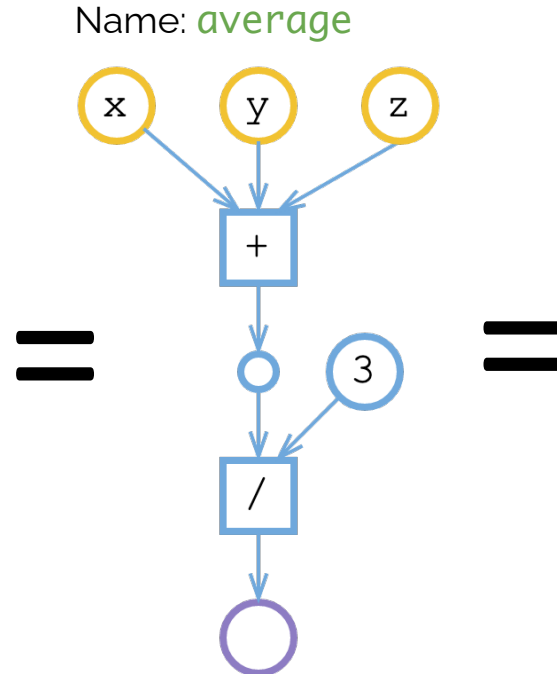
Syntax

$p \in \text{Program}$	$::=$	R
$r \in R \subseteq \text{Reactor}$	$::=$	$\mathcal{R}\langle x, N \rangle$
$n \in N \subseteq \text{Node}$	$::=$	(\bar{i}, nt, \bar{o})
$i \in \text{Input Port}$	$::=$	$x \mid v$
$nt \in \text{Node Type}$	$::=$	$\mathcal{RHO}\langle N \rangle$ $DEPLOY$
$o \in \text{Output Port}$	$::=$	x
		$x \in X \subseteq \text{Name}$
		$\{in_{i,j}, out_{i,j} \mid \forall i \in \mathbb{N}^+, \forall j \in \mathbb{N}\} \subseteq X$
		$v \in V \subseteq \text{Domain Value}$

Anonymous, nested, graph definitions with lexical scope.

```
(defr (average x y z)
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```

Haai Syntax



Graph Visualisation

```
r_avg = R( average,
  {([+, in1,0, in2,0, in3,0], DEPLOY, [s0]),
  ([/, s0, 3], DEPLOY, [out1,0])}
```

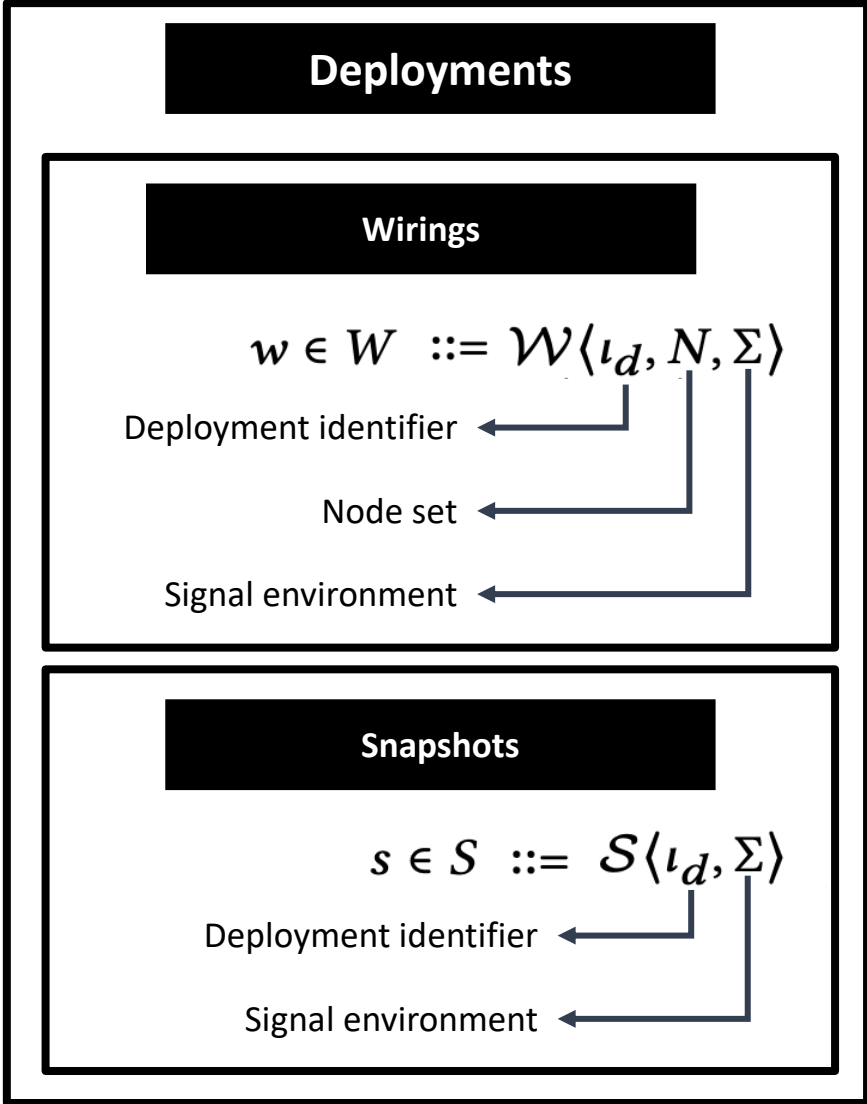
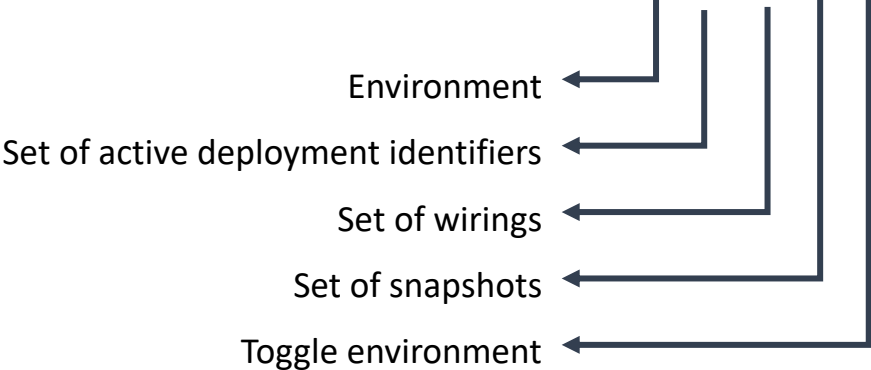
Special input names ($in_{i,j}$)

Special output names ($out_{i,j}$)

Karcharias Syntax

Configurations

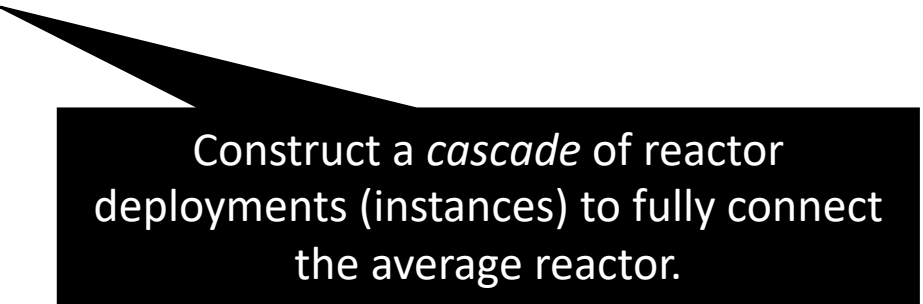
$$k ::= \mathcal{K}\langle E, I_d, W, S, D \rangle$$



Main Idea: Signal Environments

```
(defn average x y z)  
  (/ (+ x y z) 3))
```

```
(average sensor0 sensor1 sensor2)
```



Construct a *cascade* of reactor deployments (instances) to fully connect the average reactor.

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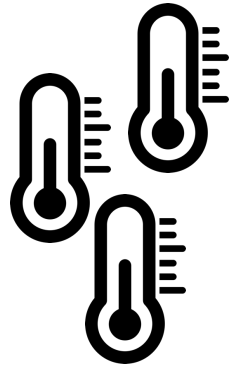
```
(average sensor0 sensor1 sensor2)
```

average ($\iota_{d,avg}$)	
<i>Name</i>	<i>Signal</i>
in _{1,0}	
in _{2,0}	
in _{3,0}	
s ₀	
out _{1,0}	

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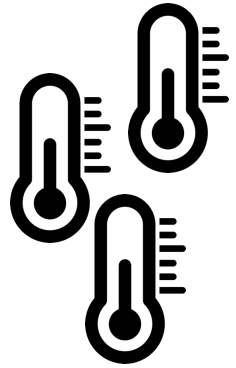
average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$S_{GLB}\langle \text{sensor0} \rangle$
in _{2,0}	$S_{GLB}\langle \text{sensor1} \rangle$
in _{3,0}	$S_{GLB}\langle \text{sensor2} \rangle$
s ₀	
out _{1,0}	

Semantic entities that refer to global signals.

$\sigma \subseteq \mathbf{Signal} ::= v$
 $\quad \quad \quad \quad \quad \quad \quad \quad S_{GLB}\langle x \rangle$
 $\quad \quad \quad \quad \quad \quad \quad \quad S_{REF}\langle \sigma, x \rangle$
 $\quad \quad \quad \quad \quad \quad \quad \quad S_{DEP}\langle \iota_b, \sigma, \bar{\sigma} \rangle$

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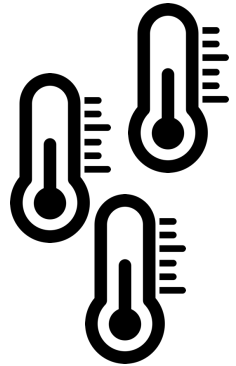


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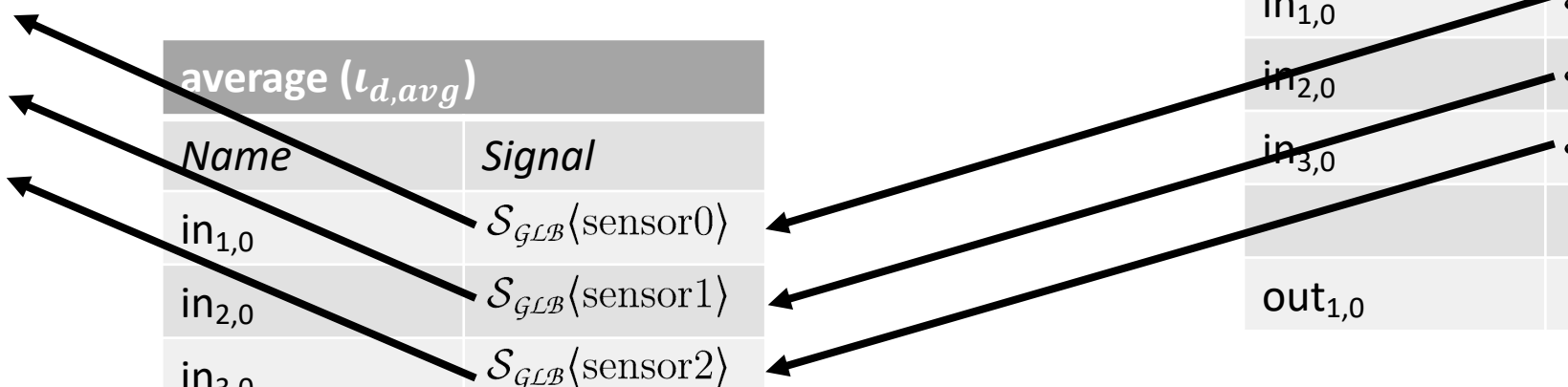
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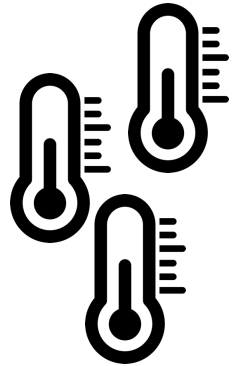
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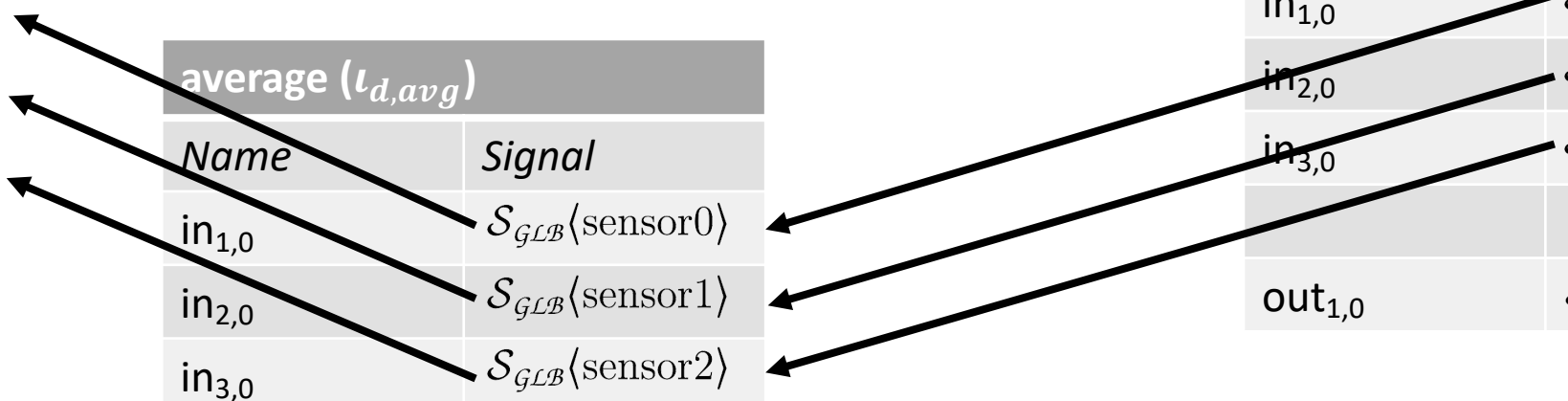
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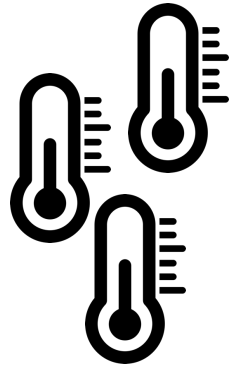
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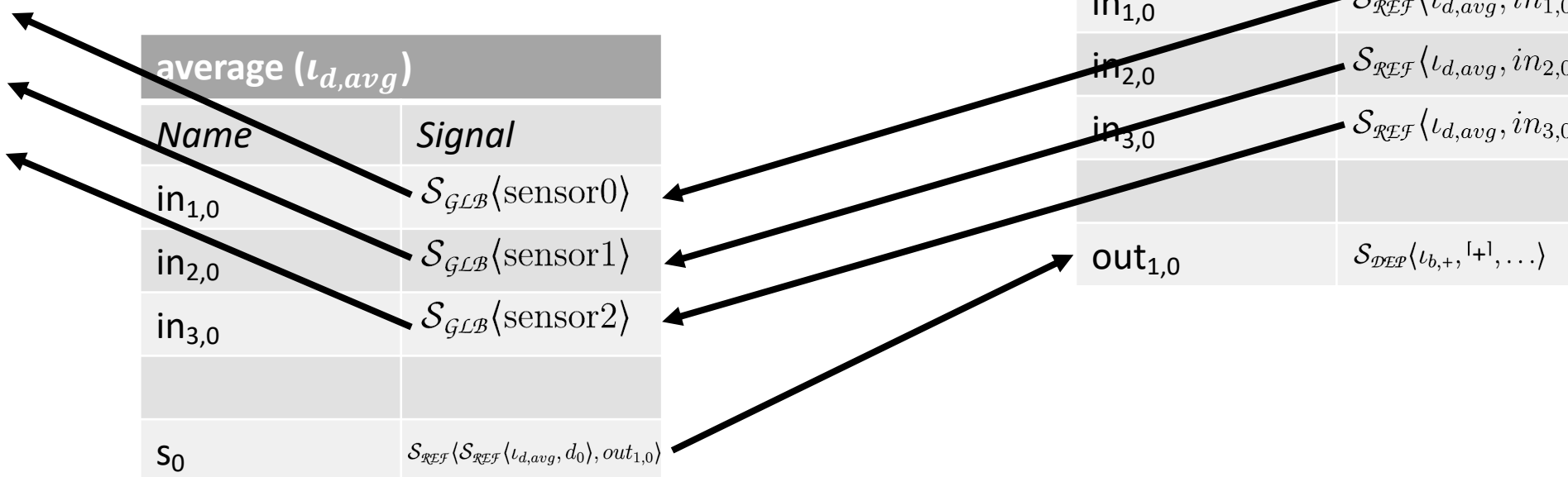
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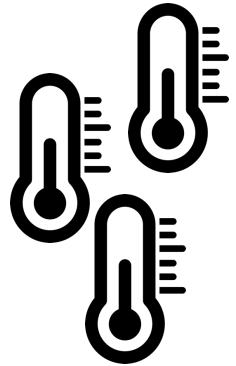
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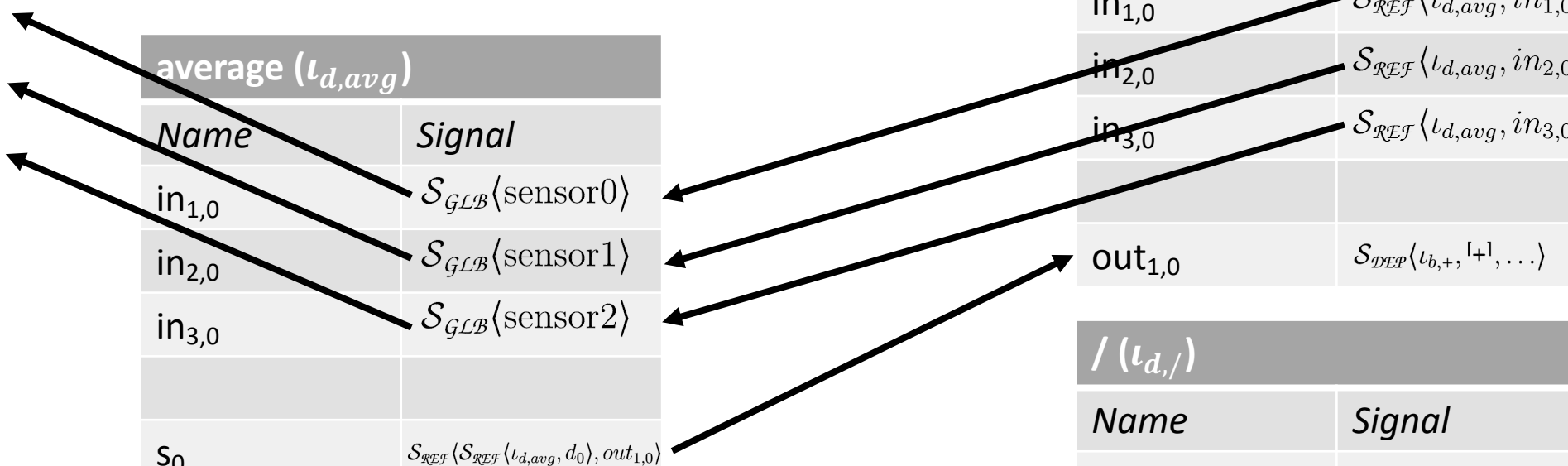
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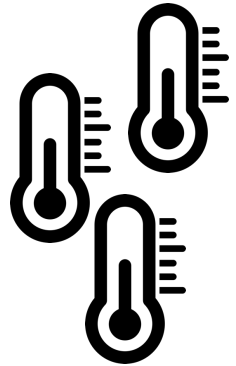
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out _{1,0}	



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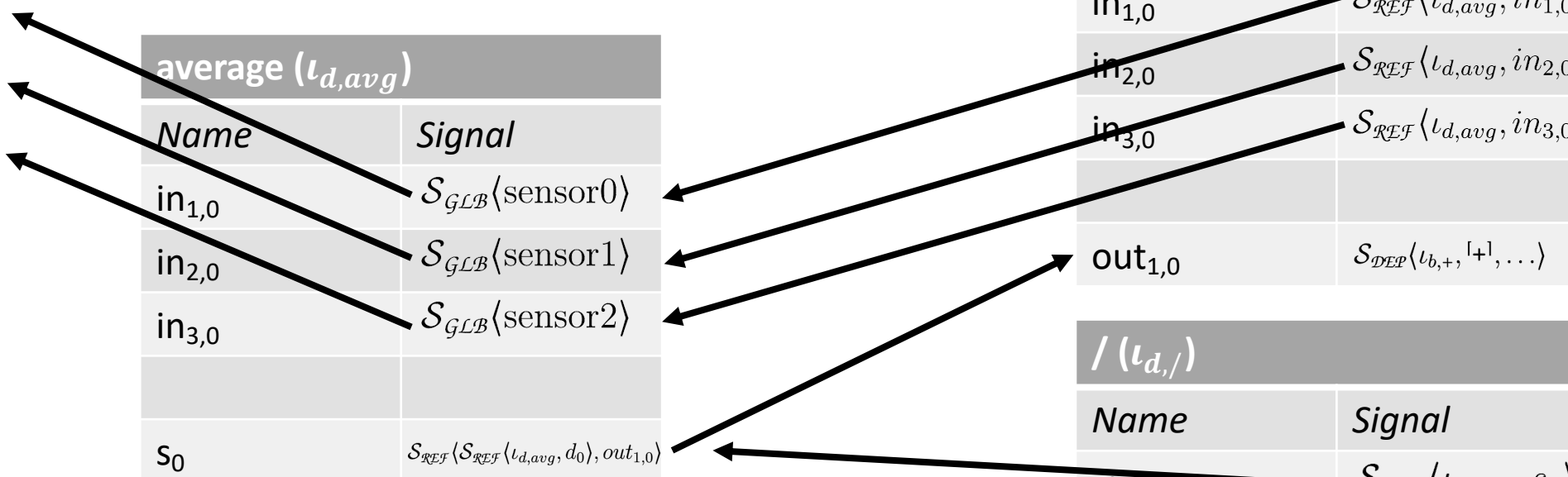
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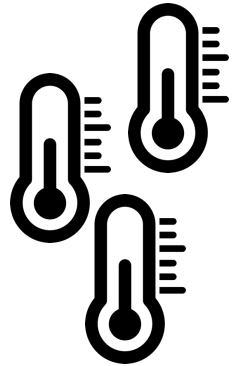
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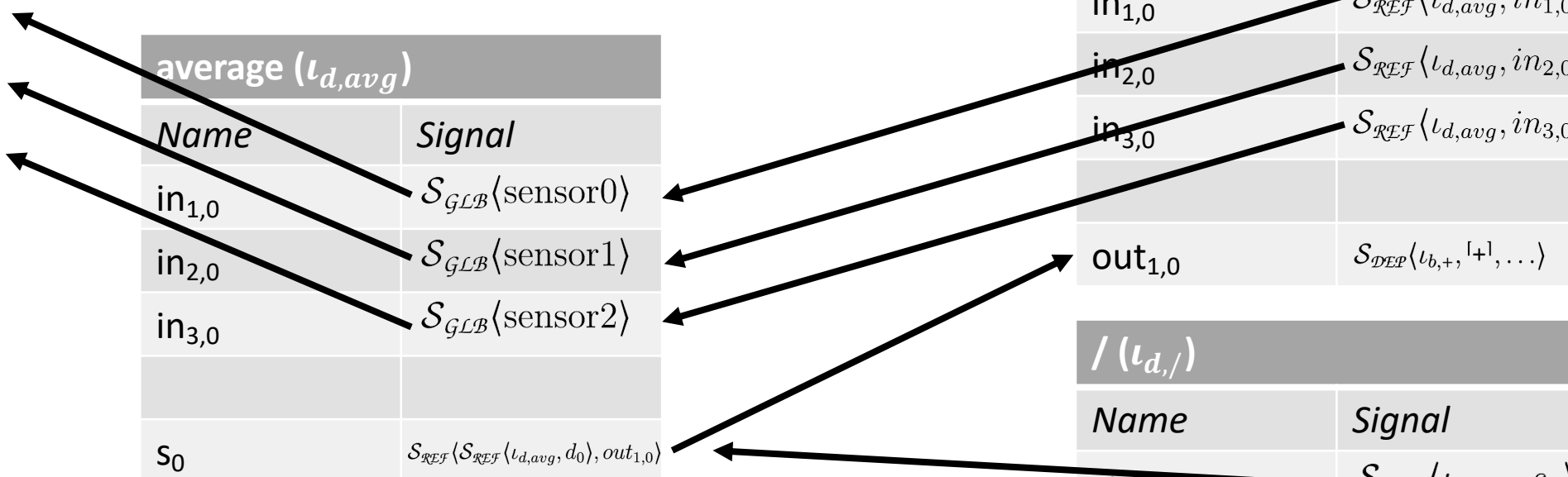
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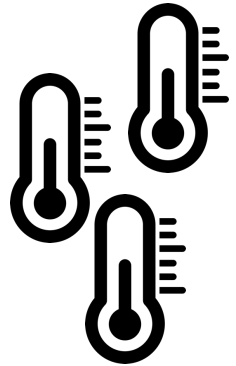
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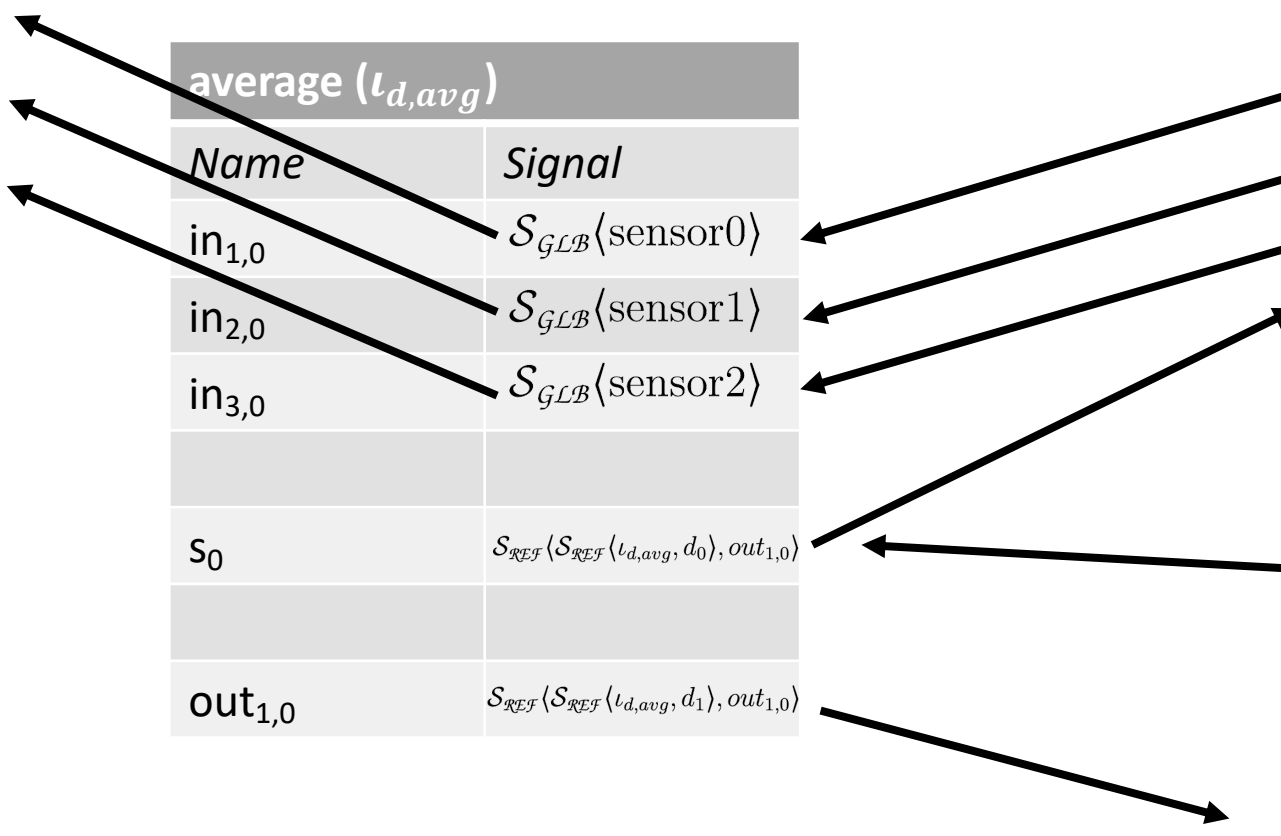
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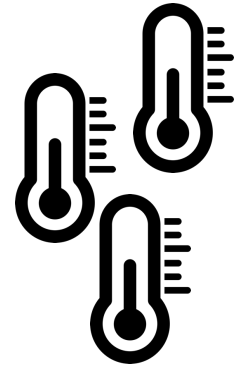
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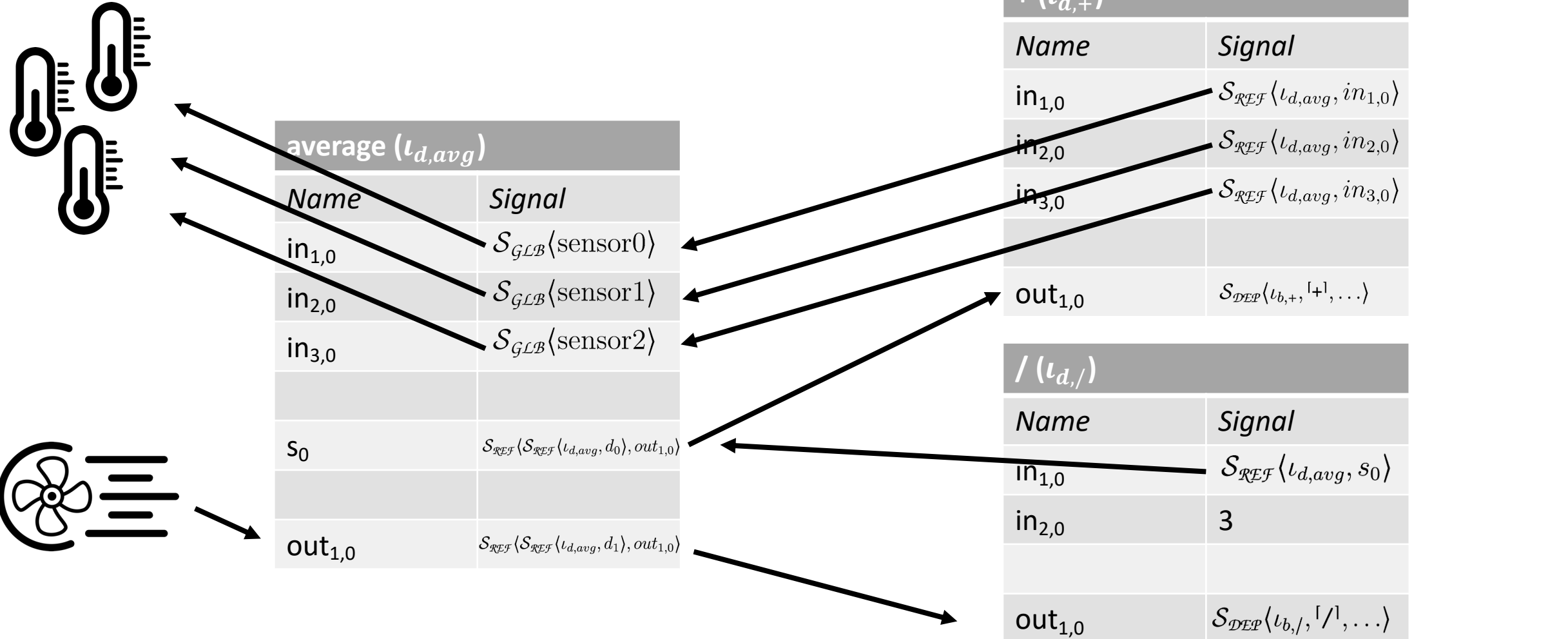
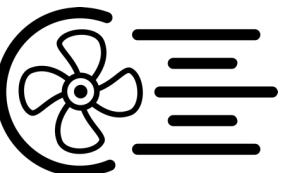
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{GLB}\langle \text{sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{GLB}\langle \text{sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{GLB}\langle \text{sensor2} \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
out _{1,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,+}, \uparrow^+, \dots \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, s_0 \rangle$
in _{2,0}	3
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,/}, \uparrow^/, \dots \rangle$



Wiring (W-Rules)

- Connect signals between deployments
- Signal environment is populated step-by-step

- Set of nodes

(W-REF)

$$\mathcal{W}\langle \iota_d, \{(\bar{i}_l \S [x] \S \bar{i}_r, nt, \bar{o})\} \cup N, \Sigma \rangle \rightarrow_w \mathcal{W}\langle \iota_d, \{(\bar{i}_l \S [\Sigma(x)] \S \bar{i}_r, nt, \bar{o})\} \cup N, \Sigma \rangle$$

Local Wiring Rules (\rightarrow_w):

(W-REF)

$$\mathcal{W}\langle \iota_d, \{(\bar{i}_l \S [x] \S \bar{i}_r, nt, \bar{o})\} \cup N, \Sigma \rangle \rightarrow_w \mathcal{W}\langle \iota_d, \{(\bar{i}_l \S [\Sigma(x)] \S \bar{i}_r, nt, \bar{o})\} \cup N, \Sigma \rangle$$

(W-DEPLOY)

$$\frac{x, \iota_b \text{ fresh} \quad \Sigma' = \Sigma[x \mapsto \mathcal{S}_{DEP}\langle \iota_b, \sigma, \bar{\sigma} \rangle][o_i \mapsto \mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_d, x \rangle, out_{i,0} \rangle \mid \forall i \in [1..|\bar{o}|]]}{N, \Sigma \rangle \rightarrow_w \mathcal{W}\langle \iota_d, N, \Sigma' \rangle}$$

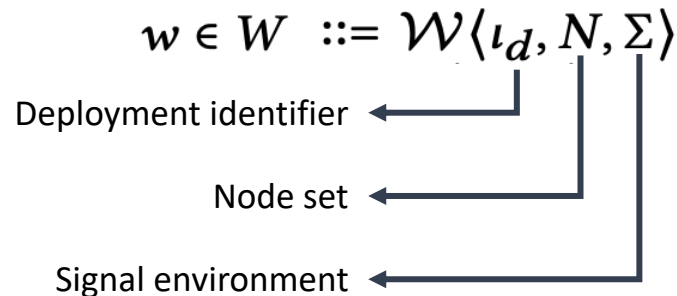
$$\frac{c = \mathcal{C}\langle \iota_c, N_{inner}, \Sigma_c \rangle}{\Sigma \rangle \rightarrow_w \mathcal{W}\langle \iota_d, N, \Sigma[o \mapsto c] \rangle}$$

$$\text{Where } \text{shift_io}(\Sigma) = \{x' \mapsto \sigma \mid \forall x \mapsto \sigma \in \Sigma, x' = \begin{cases} in_{i,j+1} & x = in_{i,j} \\ out_{i,j+1} & x = out_{i,j} \\ x & \text{otherwise} \end{cases}$$

Global Rules (\rightarrow_k):

(W-CONGRUENCE)

$$\frac{w \rightarrow_w w'}{\mathcal{K}\langle E, I_d, \{w\} \cup W, S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, \{w'\} \cup W, S, D \rangle}$$



$$w_{avg} = \mathcal{W}\langle \iota_{d,avg}, \{([+, in_{1,0}, in_{2,0}, in_{3,0}], \mathcal{DEPLOY}, [x]) ([/, x, 3], \mathcal{DEPLOY}, [out_{1,0}])\}, \{in_{1,0} \mapsto \mathcal{S}_{REF}\langle \dots \rangle, \dots, time \mapsto \mathcal{S}_{GLB}\langle time \rangle, \dots\} \rangle$$



$$w'_{avg} = \mathcal{W}\langle \iota_{d,avg}, \{([/, x, 3], \mathcal{DEPLOY}, [out_{1,0}])\}, \{x \mapsto \mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle, in_{1,0} \mapsto \mathcal{S}_{REF}\langle \dots \rangle, \dots, time \mapsto \mathcal{S}_{GLB}\langle time \rangle, \dots\} \rangle$$



$$w''_{avg} = \mathcal{W}\langle \iota_{d,avg}, \{\}, \{out_{1,0} \mapsto \mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_2 \rangle, out_{1,0} \rangle, x \mapsto \mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle, in_{1,0} \mapsto \mathcal{S}_{REF}\langle \dots \rangle, \dots, time \mapsto \mathcal{S}_{GLB}\langle time \rangle, \dots\} \rangle$$

$$w \in W ::= \mathcal{W}\langle \iota_d, N, \Sigma \rangle$$

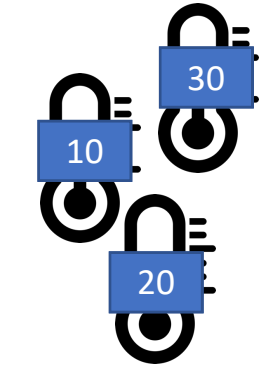
Deployment identifier ←

Node set ←

Signal environment ←

(defr (average x y z)
 (/ (+ x y z) 3))

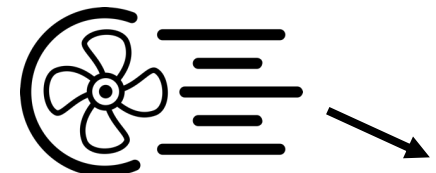
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{GLB}\langle \text{sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{GLB}\langle \text{sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{GLB}\langle \text{sensor2} \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
out _{1,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

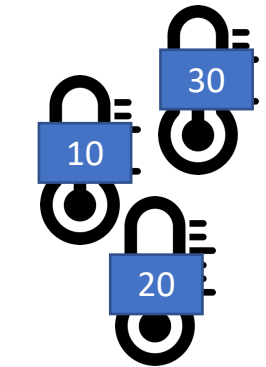
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,+}, \uparrow^+, \dots \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, s_0 \rangle$
in _{2,0}	3
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,/}, \uparrow^/, \dots \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

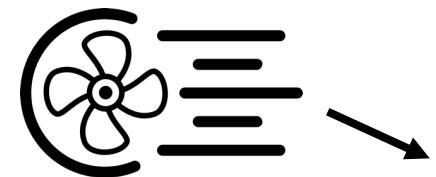
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_2 \rangle, out_{1,0} \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
out _{1,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

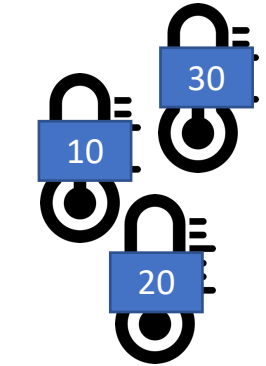
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,+}, \uparrow^+, \dots \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, s_0 \rangle$
in _{2,0}	3
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,/}, \uparrow^/, \dots \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

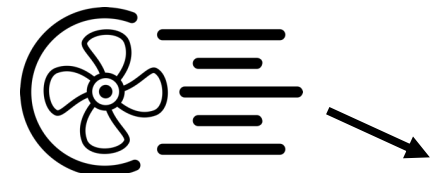
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
in _{2,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$
in _{3,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_2 \rangle, out_{1,0} \rangle$
S ₀	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
out _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

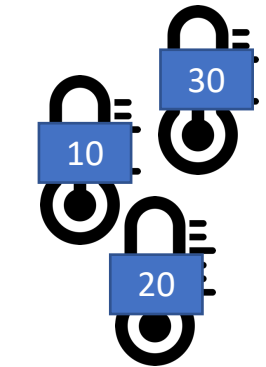
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, in_{1,0} \rangle, out_{1,0} \rangle$
in _{2,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, in_{2,0} \rangle, out_{1,0} \rangle$
in _{3,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, in_{3,0} \rangle, out_{1,0} \rangle$
out _{1,0}	$S_{\text{DEP}}\langle \iota_{b,+}, \uparrow^+, \dots \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$S_{\text{REF}}\langle \iota_{d,avg}, S_0 \rangle$
in _{2,0}	3
out _{1,0}	$S_{\text{DEP}}\langle \iota_{b,/}, \uparrow^/, \dots \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

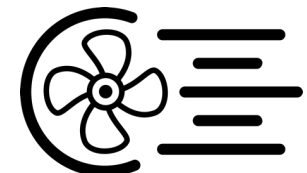
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
in _{2,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$
in _{3,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_2 \rangle, out_{1,0} \rangle$
S ₀	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
out _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

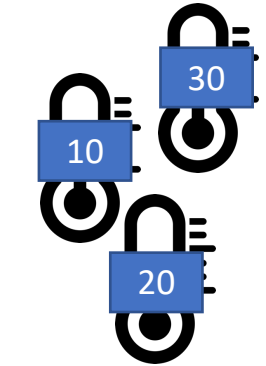
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, in_{1,0} \rangle, out_{1,0} \rangle$
in _{2,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, in_{2,0} \rangle, out_{1,0} \rangle$
in _{3,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, in_{3,0} \rangle, out_{1,0} \rangle$
out _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,+}, out_{1,0} \rangle, out_{1,0} \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,/}, in_{1,0} \rangle, out_{1,0} \rangle$
in _{2,0}	3
out _{1,0}	$S_{\text{REF}}\langle S_{\text{REF}}\langle \iota_{d,/}, out_{1,0} \rangle, out_{1,0} \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

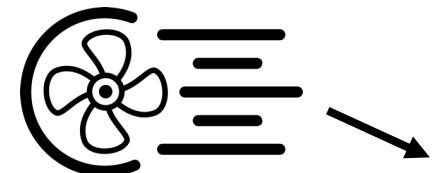
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 10, \text{sensor0} \rangle$
in _{2,0}	$S_{REF} \langle 20, \text{sensor1} \rangle$
in _{3,0}	$S_{REF} \langle 30, \text{sensor2} \rangle$
s ₀	$S_{REF} \langle 60, \text{avg}, d_0 \rangle, \text{out}_{1,0} \rangle$
out _{1,0}	$S_{REF} \langle S_{REF} \langle \iota_{d,avg}, d_1 \rangle, \text{out}_{1,0} \rangle$

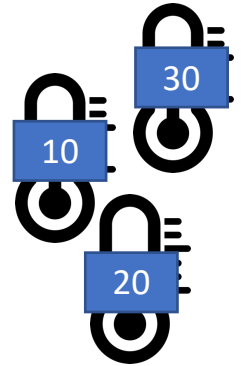
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 10, \text{avg}, \text{in}_{1,0} \rangle$
in _{2,0}	$S_{REF} \langle 20, \text{avg}, \text{in}_{2,0} \rangle$
in _{3,0}	$S_{REF} \langle 30, \text{avg}, \text{in}_{3,0} \rangle$
out _{1,0}	$S_{REF} \langle 60, \text{avg}, \text{in}_{1,0}, \text{in}_{2,0}, \text{in}_{3,0} \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle \iota_{d,avg}, s_0 \rangle$
in _{2,0}	3
out _{1,0}	$S_{DEF} \langle \iota_{b,/}, \text{in}_{1,0}, \text{in}_{2,0} \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

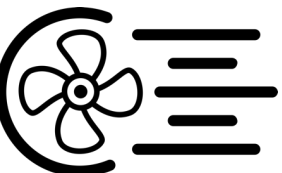
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 10, \text{sensor0} \rangle$
in _{2,0}	$S_{REF} \langle 20, \text{sensor1} \rangle$
in _{3,0}	$S_{REF} \langle 30, \text{sensor2} \rangle$
S ₀	$S_{REF} \langle 60, \text{avg}, d_0 \rangle, \text{out}_{1,0} \rangle$
out _{1,0}	$S_{REF} \langle S_{REF} \langle \iota_{d,avg}, d_1 \rangle, \text{out}_{1,0} \rangle$

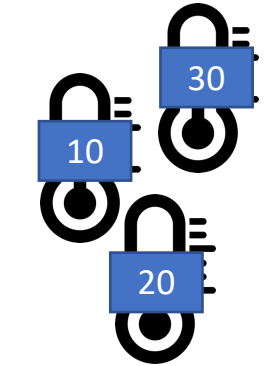
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 10, \text{avg}, \text{in}_{1,0} \rangle$
in _{2,0}	$S_{REF} \langle 20, \text{avg}, \text{in}_{2,0} \rangle$
in _{3,0}	$S_{REF} \langle 30, \text{avg}, \text{in}_{3,0} \rangle$
out _{1,0}	$S_{REF} \langle 60, \text{avg}, \text{in}_{1,0}, \text{in}_{2,0}, \text{in}_{3,0} \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 60, \text{avg}, S_0 \rangle$
in _{2,0}	3
out _{1,0}	$S_{REF} \langle \iota_{b,/}, \text{in}_{1,0}, \text{in}_{2,0} \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

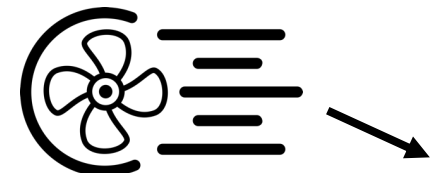
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 10, \text{sensor0} \rangle$
in _{2,0}	$S_{REF} \langle 20, \text{sensor1} \rangle$
in _{3,0}	$S_{REF} \langle 30, \text{sensor2} \rangle$
S ₀	$S_{REF} \langle 60, \text{avg}, d_0 \rangle, \text{out}_{1,0} \rangle$
out _{1,0}	$S_{REF} \langle S_{REF} \langle \iota_{d,avg}, d_1 \rangle, \text{out}_{1,0} \rangle$

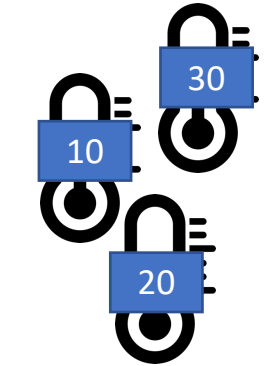
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 10, \text{avg}, \text{in}_{1,0} \rangle$
in _{2,0}	$S_{REF} \langle 20, \text{avg}, \text{in}_{2,0} \rangle$
in _{3,0}	$S_{REF} \langle 30, \text{avg}, \text{in}_{3,0} \rangle$
out _{1,0}	$S_{REF} \langle 60, \text{+}, \dots \rangle$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	$S_{REF} \langle 60, \text{d,avg}, S_0 \rangle$
in _{2,0}	3
out _{1,0}	$S_{REF} \langle 20, \text{/}, \dots \rangle$



(defr (average x y z)
 (/ (+ x y z) 3))

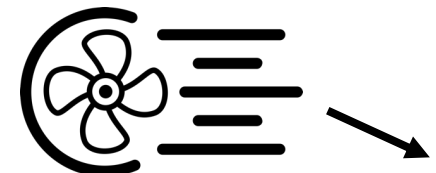
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	S_{REF} 10 sensor0
in _{2,0}	S_{REF} 20 sensor1
in _{3,0}	S_{REF} 30 sensor2
s ₀	S_{REF} 60 $\iota_{d,avg}, d_0, out_{1,0}$
out _{1,0}	S_{REF} 20 $\iota_{d,avg}, d_1, out_{1,0}$

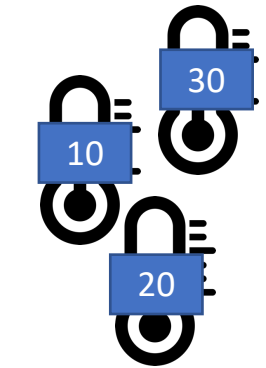
+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	S_{REF} 10 $\iota_{d,+}, in_{1,0}$
in _{2,0}	S_{REF} 20 $\iota_{d,+}, in_{2,0}$
in _{3,0}	S_{REF} 30 $\iota_{d,+}, in_{3,0}$
out _{1,0}	S_{REF} 60 $\iota_{d,+}, \dots$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	S_{REF} 60 $\iota_{d,/}, \iota_{d,avg}, s_0$
in _{2,0}	3
out _{1,0}	S_{REF} 20 $\iota_{d,/}, \dots$



(defr (average x y z)
 (/ (+ x y z) 3))

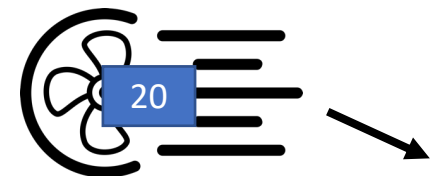
Main Idea: Signal Environments



average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	S_{REF} 10 sensor0
in _{2,0}	S_{REF} 20 sensor1
in _{3,0}	S_{REF} 30 sensor2
s ₀	S_{REF} 60 $\iota_{d,avg}, d_0, out_{1,0}$
out _{1,0}	S_{REF} 20 $\iota_{d,avg}, d_1, out_{1,0}$

+ ($\iota_{d,+}$)	
Name	Signal
in _{1,0}	S_{REF} 10 $\iota_{d,+}, in_{1,0}$
in _{2,0}	S_{REF} 20 $\iota_{d,+}, in_{2,0}$
in _{3,0}	S_{REF} 30 $\iota_{d,+}, in_{3,0}$
out _{1,0}	S_{REF} 60 $\iota_{d,+}, \dots$

/ ($\iota_{d,/}$)	
Name	Signal
in _{1,0}	S_{REF} 60 $\iota_{d,/}, \iota_{d,avg}, s_0$
in _{2,0}	3
out _{1,0}	S_{REF} 20 $\iota_{d,/}, \dots$



Propagation (S-Rules)

- Reduce signal's into their current values.
- S-rules define the semantics of computing a **snapshot**.



Evaluation Contexts:

$$\begin{aligned} \mathcal{E} & ::= \{x \mapsto \mathcal{E}_\sigma\} \cup \Sigma \\ \mathcal{E}_\sigma & ::= \square \\ & \quad | \mathcal{S}_{REF}\langle \mathcal{E}_\sigma, x \rangle \\ & \quad | \mathcal{S}_{DEP}\langle \iota_b, \mathcal{E}_\sigma, \bar{\sigma} \rangle \\ & \quad | \mathcal{S}_{DEP}\langle \iota_b, p, \bar{\sigma} \S [\mathcal{E}_\sigma] \S \bar{\sigma} \rangle \end{aligned}$$

Evaluation Contexts:

$$\begin{aligned} \mathcal{E} & ::= \{x \mapsto \mathcal{E}_\sigma\} \cup \Sigma \\ \mathcal{E}_\sigma & ::= \square \\ & \quad | \mathcal{S}_{REF}\langle \mathcal{E}_\sigma, x \rangle \\ & \quad | \mathcal{S}_{DEP}\langle \iota_b, \mathcal{E}_\sigma, \bar{\sigma} \rangle \\ & \quad | \mathcal{S}_{DEP}\langle \iota_b, p, \bar{\sigma} \S [\mathcal{E}_\sigma] \S \bar{\sigma} \rangle \end{aligned}$$

$\mathcal{K}\langle E, I_d, W, \{s\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, W, \{s'\} \cup S, D \rangle$ (S-REF)

$\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma' \rangle\} \cup S, D \rangle$ (S-GLOBAL)

$\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, \{i'_d\} \cup I_d, \{w\} \cup W, \{S\langle \iota_d, \Sigma' \rangle\} \cup S, D' \rangle$ (S-DEPLOY-EXISTING)

$\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle$ (S-REF)

$\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma' \rangle\} \cup S, D \rangle$ (S-GLOBAL)

$\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, \{i'_d\} \cup I_d, \{w\} \cup W, \{S\langle \iota_d, \Sigma' \rangle\} \cup S, D' \rangle$ (S-DEPLOY-EXISTING)

(S-GLOBAL)

$$\frac{\Sigma = \mathcal{E}[\mathcal{S}_{GLB}\langle x \rangle] \quad \Sigma' = \mathcal{E}[E(x)]}{\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma' \rangle\} \cup S, D \rangle}$$

(S-DEPLOY-EXISTING)

$$\frac{\Sigma = \mathcal{E}[\mathcal{S}_{DEP}\langle \iota_b, C\langle \iota_c, N, \Sigma_c \rangle, \bar{\sigma} \rangle] \quad i'_d = D(\iota_b, \iota_c) \quad \Sigma' = \mathcal{E}[i'_d]}{\mathcal{K}\langle E, I_d, W, \{S\langle \iota_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K}\langle E, \{i'_d\} \cup I_d, W, \{S\langle \iota_d, \Sigma' \rangle\} \cup S, D \rangle}$$

$$s_{avg} = \mathcal{S} \langle \iota_{d,avg}, \{ \text{out}_{1,0} \mapsto \mathcal{S}_{REF} \langle \mathcal{S}_{REF} \langle \iota_{d,avg}, d_2 \rangle, \text{out}_{1,0} \rangle, x \mapsto \mathcal{S}_{REF} \langle \mathcal{S}_{REF} \langle \iota_{d,avg}, d_1 \rangle, \text{out}_{1,0} \rangle, \text{in}_{1,0} \mapsto \mathcal{S}_{REF} \langle \dots \rangle, \dots, \text{time} \mapsto \mathcal{S}_{GLB} \langle \text{time} \rangle, \dots \} \rangle$$



$$s'_{avg} = \mathcal{S} \langle \iota_{d,avg}, \{ \text{out}_{1,0} \mapsto \mathcal{S}_{REF} \langle \mathcal{S}_{REF} \langle \iota_{d,avg}, d_2 \rangle, \text{out}_{1,0} \rangle, x \mapsto \mathcal{S}_{REF} \langle \mathcal{S}_{REF} \langle \iota_{d,avg}, d_1 \rangle, \text{out}_{1,0} \rangle, \text{in}_{1,0} \mapsto 10, \text{in}_{2,0} \mapsto 20, \text{in}_{3,0} \mapsto 30, \text{time} \mapsto 1, \dots \} \rangle$$



$$s''_{avg} = \mathcal{S} \langle \iota_{d,avg}, \{ \text{out}_{1,0} \mapsto 20, x \mapsto 60, \text{in}_{1,0} \mapsto 10, \text{in}_{2,0} \mapsto 20, \text{in}_{3,0} \mapsto 30, \text{time} \mapsto 1, \dots \} \rangle$$



It's not that easy...

```
(defn (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

Sometimes +, sometimes *.
(e.g., (if (even? time) + *))

```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

Higher-Order Reactivity

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{GLB}\langle \text{sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{GLB}\langle \text{sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{GLB}\langle \text{sensor2} \rangle$
S ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
...	...

Wiring decision is made at-propagation time, not at wiring time.

?

+ ($\iota_{d,+}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEP}\langle \iota_{b,+}, \iota_{+}^1, \dots \rangle$

* ($\iota_{d,*}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	

Higher-Order Reactivity

```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{GLB}\langle \text{sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{GLB}\langle \text{sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{GLB}\langle \text{sensor2} \rangle$
d ₀	$\mathcal{S}_{DEF}\langle \iota_{b,d}, \mathcal{S}_{REF}\langle \iota_{d,avg}, +-or^* \rangle, \dots \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
...	...

Meta signal with the deployment identifier (ι_d)

?

+ ($\iota_{d,+}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEF}\langle \iota_{b,+}, \iota_{+}^1, \dots \rangle$

* ($\iota_{d,*}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	

```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

Higher-Order Reactivity

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle 10 \text{ sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle 20 \text{ sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle 30 \text{ sensor2} \rangle$
d ₀	$\mathcal{S}_{DEF}\langle \iota_{b,d}, \mathcal{S}_{REF}\langle \iota_{d,avg}, +-or^* \rangle, \dots \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
...	...

Meta signal with the deployment identifier (ι_d)

?

+ ($\iota_{d,+}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEF}\langle \iota_{b,+}, \iota_{+}^1, \dots \rangle$

* ($\iota_{d,*}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	

Higher-Order Reactivity

```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle 10 \text{ sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle 20 \text{ sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle 30 \text{ sensor2} \rangle$
d ₀	$\mathcal{S}_{DEF}\langle \mathbf{\iota_{d,*}} \langle \iota_{d,avg}, +-or^* \rangle, \dots \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
...	...

Meta signal with the deployment identifier (ι_d)

?

+ ($\iota_{d,+}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEF}\langle \iota_{b,+}, \iota_{+}^1, \dots \rangle$

* ($\iota_{d,*}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	

Higher-Order Reactivity

```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

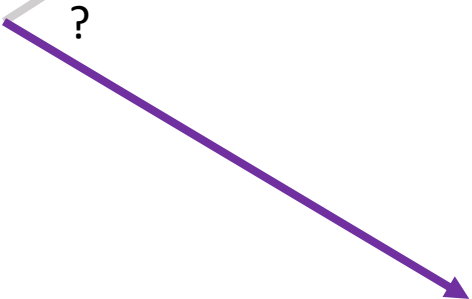
Deployment disabled
(its output is not used in this turn)

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	$\mathcal{S}_{REF}\langle 10 \text{ sensor0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle 20 \text{ sensor1} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle 30 \text{ sensor2} \rangle$
d ₀	$\mathcal{S}_{DEF}\langle \mathbf{\iota_{d,*}} \langle \iota_{d,avg}, +-or^* \rangle, \dots \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
...	...

Meta signal with the deployment identifier (ι_d)

+ ($\iota_{d,+}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	$\mathcal{S}_{DEF}\langle \iota_{b,+}, \iota_{d,+}^1, \dots \rangle$

* ($\iota_{d,*}$)	
Name	Value
in _{1,0}	$\mathcal{S}_{REF}\langle 10 \iota_{d,avg}, in_{1,0} \rangle$
in _{2,0}	$\mathcal{S}_{REF}\langle 20 \iota_{d,avg}, in_{2,0} \rangle$
in _{3,0}	$\mathcal{S}_{REF}\langle 30 \iota_{d,avg}, in_{3,0} \rangle$
out _{1,0}	



```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

Higher-Order Reactivity

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	& 10 sensor0}
in _{2,0}	& 20 sensor1}
in _{3,0}	& 30 sensor2}
d ₀	$\mathcal{S}_{DEF}\langle \iota_{b,d}, \mathcal{S}_{REF}\langle \iota_{d,avg}, +-or^* \rangle, \dots \rangle$
s ₀	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
d ₁	$\mathcal{S}_{DEF}\langle \iota'_{b,d}, \mathcal{S}_{GLB}\langle / \rangle, \dots \rangle$
out _{1,0}	$\mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

What happens in the very first turn?


```
(defr (weird x y z)
  (def +or* ...)
  (/ (+or* x y z) 3))
```

Higher-Order Reactivity

average ($\iota_{d,avg}$)	
Name	Signal
in _{1,0}	& 10 sensor0}
in _{2,0}	& 20 sensor1}
in _{3,0}	& 30 sensor2}
d ₀	$S_{DEF} \langle \iota_{d,*} (\iota_{d,avg}, +-or-*) , \dots \rangle$
s ₀	$S_{REF} \langle S_{REF} \langle \iota_{d,avg}, d_0 \rangle, out_{1,0} \rangle$
d ₁	$S_{DEP} \langle \iota'_{b,d}, S_{GLB} \langle / \rangle , \dots \rangle$
out _{1,0}	$S_{REF} \langle S_{REF} \langle \iota_{d,avg}, d_1 \rangle, out_{1,0} \rangle$

* ($\iota_{d,*}$)	
Name	Value
in _{1,0}	
in _{2,0}	
in _{3,0}	
out _{1,0}	

When "evaluating" the meta signal, the new deployment is created.

W-Rules and S-Rules can be interleaved!

- Dynamically create new deployments for new captures (reactors) on the operator signals.

(W-DEPLOY)

$$\frac{x, \iota_b \text{ fresh} \quad \Sigma' = \Sigma[x \mapsto \mathcal{S}_{\mathcal{DEP}} \langle \iota_b, \sigma, \bar{\sigma} \rangle][o_i \mapsto \mathcal{S}_{\mathcal{REF}} \langle \mathcal{S}_{\mathcal{REF}} \langle \iota_d, x \rangle, out_{i,0} \rangle \mid \forall i \in [1..|\bar{o}|]]}{\mathcal{W} \langle \iota_d, \{([\sigma] \S \bar{\sigma}, \mathcal{DEPLOY}, \bar{o})\} \cup N, \Sigma \rangle \rightarrow_w \mathcal{W} \langle \iota_d, N, \Sigma' \rangle}$$

W-Rules and S-Rules can be interleaved!

- Dynamically create new deployments for new captures (reactors) on the operator signals.

Stored in the configuration.

Toggle Environment

$$D ::= \{(l_b, l_c) \mapsto l_d, \dots\}$$

Branching location identifier

Capture (reactor) identifier

Deployment identifier

Evaluation Contexts:

$$\begin{aligned} \mathcal{E} & ::= \{x \mapsto \mathcal{E}_\sigma\} \cup \Sigma \\ \mathcal{E}_\sigma & ::= \square \\ & \quad | \mathcal{S}_{REF} \langle \mathcal{E}_\sigma, x \rangle \\ & \quad | \mathcal{S}_{DEP} \langle l_b, \mathcal{E}_\sigma, \bar{\sigma} \rangle \\ & \quad | \mathcal{S}_{DEP} \langle l_b, p, \bar{\sigma} \S [\mathcal{E}_\sigma] \S \bar{\sigma} \rangle \end{aligned}$$

(S-ACTIVATE)

$$\frac{\mathcal{W} \langle l_d, \emptyset, \Sigma \rangle \in W \quad l_d \in I_d \quad \forall s \in S : s = \mathcal{S} \langle l'_d, \Sigma' \rangle, l_d \neq l'_d}{\mathcal{K} \langle E, I_d, W, S, D \rangle \rightarrow_k \mathcal{K} \langle E, I_d, W, \{\mathcal{S} \langle l_d, \Sigma \rangle\} \cup S, D \rangle}$$

(S-DEPLOY-NEW)

$$\frac{\begin{aligned} \Sigma &= \mathcal{E}[\mathcal{S}_{DEP} \langle l_b, \mathcal{C} \langle l_c, N, \Sigma_c \rangle, \bar{\sigma} \rangle] \quad (l_b, l_c) \notin \text{dom}(D) \quad l'_d \text{ fresh} \\ w &= \mathcal{W} \langle l'_d, N, \Sigma_c[in_{i,0} \mapsto \sigma_i \mid \forall i \in [1..|\bar{\sigma}|]] \rangle \quad \Sigma' = \mathcal{E}[l'_d] \\ D' &= D[(l_b, l_c) \mapsto l'_d] \end{aligned}}{\mathcal{K} \langle E, I_d, W, \{\mathcal{S} \langle l_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K} \langle E, \{l'_d\} \cup I_d, \{w\} \cup W, \{\mathcal{S} \langle l_d, \Sigma' \rangle\} \cup S, D' \rangle}$$

(S-DEPLOY-EXISTING)

$$\frac{\Sigma = \mathcal{E}[\mathcal{S}_{DEP} \langle l_b, \mathcal{C} \langle l_c, N, \Sigma_c \rangle, \bar{\sigma} \rangle] \quad l'_d = D(l_b, l_c) \quad \Sigma' = \mathcal{E}[l'_d]}{\mathcal{K} \langle E, I_d, W, \{\mathcal{S} \langle l_d, \Sigma \rangle\} \cup S, D \rangle \rightarrow_k \mathcal{K} \langle E, \{l'_d\} \cup I_d, W, \{\mathcal{S} \langle l_d, \Sigma' \rangle\} \cup S, D \rangle}$$

W-Rules and S-Rules can be interleaved!

- Dynamically create new deployments for new captures (reactors) on the operator signals.
- One reduction relation (\rightarrow_k)
 - Two helper relations (\rightarrow_w and \rightarrow_s)
 - Both local and global wiring and snapshot rules.

Local Wiring Rules (\rightarrow_w):

$$\begin{array}{c} \text{(W-REF)} \\ \mathcal{W}\langle t_d, \{(\bar{i}_l \S [x] \S \bar{i}_r, nt, \bar{o})\} \cup N, \Sigma \rangle \\ \rightarrow_w \mathcal{W}\langle t_d, \{(\bar{i}_l \S [\Sigma(x)] \S \bar{i}_r, nt, \bar{o})\} \cup N, \Sigma \rangle \end{array}$$

$$\begin{array}{c} \text{(W-DEPLOY)} \\ x, t_b \text{ fresh} \\ \Sigma' = \Sigma[x \mapsto \mathcal{S}_{DEP}\langle t_b, \sigma, \bar{\sigma} \rangle][o_i \mapsto \mathcal{S}_{REF}\langle \mathcal{S}_{REF}\langle t_d, x \rangle, out_{i,0} \rangle \mid \forall i \in [1..|\bar{o}|]] \\ \mathcal{W}\langle t_d, \{([\sigma] \S \bar{\sigma}, DEPLOY, \bar{o})\} \cup N, \Sigma \rangle \rightarrow_w \mathcal{W}\langle t_d, N, \Sigma' \rangle \end{array}$$

$$\begin{array}{c} \text{(W-RHO)} \\ t_c \text{ fresh} \quad \Sigma_c = \text{shift_io}(\Sigma) \quad c = C\langle t_c, N_{inner}, \Sigma_c \rangle \\ \mathcal{W}\langle t_d, \{(\bar{\sigma}, \mathcal{RHO}\langle N_{inner} \rangle, [o])\} \cup N, \Sigma \rangle \rightarrow_w \mathcal{W}\langle t_d, N, \Sigma[o \mapsto c] \rangle \end{array}$$

$$\text{Where } \text{shift_io}(\Sigma) = \{x' \mapsto \sigma \mid \forall x \mapsto \sigma \in \Sigma, x' = \begin{cases} in_{i,j+1} & x = in_{i,j} \\ out_{i,j+1} & x = out_{i,j} \\ x & \text{otherwise} \end{cases}$$

Global Rules (\rightarrow_k):

$$\begin{array}{c} \text{(W-CONGRUENCE)} \\ w \rightarrow_w w' \\ \mathcal{K}\langle E, I_d, \{w\} \cup W, S, D \rangle \rightarrow_k \mathcal{K}\langle E, I_d, \{w'\} \cup W, S, D \rangle \end{array}$$

Evaluation Contexts:

$$\begin{array}{l} \mathcal{E} ::= \{x \mapsto \mathcal{E}_\sigma\} \cup \Sigma \\ \mathcal{E}_\sigma ::= \square \\ \quad \mathcal{S}_{REF}\langle \mathcal{E}_\sigma, x \rangle \\ \quad \mathcal{S}_{DEP}\langle t_b, \mathcal{E}_\sigma, \bar{\sigma} \rangle \\ \quad \mathcal{S}_{DEP}\langle t_b, p, \bar{\sigma} \rangle \S [\mathcal{E}_\sigma] \S \bar{\sigma} \end{array}$$

Local Snapshot Rules (\rightarrow_s):

$$\begin{array}{c} \text{(S-SELF-REF)} \\ \Sigma = \mathcal{E}[\mathcal{S}_{REF}\langle t_d, x \rangle] \quad v = \Sigma(x) \\ \mathcal{S}\langle t_d, \Sigma \rangle \rightarrow_s \mathcal{S}\langle t_d, \mathcal{E}[v] \rangle \end{array} \quad \begin{array}{c} \text{(S-DEPLOY-PRIMITIVE)} \\ \mathcal{S}\langle t_d, \mathcal{E}[\mathcal{S}_{DEP}\langle t_b, p, \bar{v} \rangle] \rangle \\ \rightarrow_s \mathcal{S}\langle t_d, \mathcal{E}[\delta_p(\bar{v})] \rangle \end{array}$$

$$\begin{array}{c} \text{(S-TUPLE-REF)} \\ \mathcal{S}\langle t_d, \mathcal{E}[\mathcal{S}_{REF}\langle \bar{v}, out_{(0,i)} \rangle] \rangle \\ \rightarrow_s \mathcal{S}\langle t_d, \mathcal{E}[v_i] \rangle \end{array}$$

Global Rules (\rightarrow_k):

$$\begin{array}{c} \text{(S-CONGRUENCE)} \\ s \rightarrow_s s' \\ \mathcal{K}\langle E, I_d, W, \{s\} \cup S, D \rangle \\ \rightarrow_k \mathcal{K}\langle E, I_d, W, \{s'\} \cup S, D \rangle \end{array} \quad \begin{array}{c} \text{(S-ACTIVATE)} \\ \mathcal{W}\langle t_d, \emptyset, \Sigma \rangle \in W \quad t_d \in I_d \\ \forall s \in S : s = \mathcal{S}\langle t_d, \Sigma' \rangle, t_d \neq t'_d \\ \mathcal{K}\langle E, I_d, W, S, D \rangle \\ \rightarrow_k \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma \rangle\} \cup S, D \rangle \end{array}$$

$$\begin{array}{c} \text{(S-REF)} \\ \Sigma = \mathcal{E}[\mathcal{S}_{REF}\langle t'_d, x \rangle] \quad v = \Sigma'(x) \quad \Sigma'' = \mathcal{E}[v] \\ \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma \rangle, \mathcal{S}\langle t'_d, \Sigma' \rangle\} \cup S, D \rangle \\ \rightarrow_k \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma'' \rangle, \mathcal{S}\langle t'_d, \Sigma' \rangle\} \cup S, D \rangle \end{array}$$

$$\begin{array}{c} \text{(S-GLOBAL)} \\ \Sigma = \mathcal{E}[\mathcal{S}_{GLB}(x)] \quad \Sigma' = \mathcal{E}[E(x)] \\ \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma \rangle\} \cup S, D \rangle \\ \rightarrow_k \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma' \rangle\} \cup S, D \rangle \end{array}$$

$$\begin{array}{c} \text{(S-DEPLOY-NEW)} \\ \Sigma = \mathcal{E}[\mathcal{S}_{DEP}\langle t_b, C\langle t_c, N, \Sigma_c \rangle, \bar{\sigma} \rangle] \quad (t_b, t_c) \notin \text{dom}(D) \quad i'_d \text{ fresh} \\ w = \mathcal{W}\langle t'_d, N, \Sigma_c[in_{i,0} \mapsto \sigma_i \mid \forall i \in [1..|\bar{\sigma}|]] \rangle \quad \Sigma' = \mathcal{E}[i'_d] \\ D' = D[(t_b, t_c) \mapsto i'_d] \\ \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma \rangle\} \cup S, D \rangle \\ \rightarrow_k \mathcal{K}\langle E, \{i'_d\} \cup I_d, \{w\} \cup W, \{\mathcal{S}\langle t_d, \Sigma' \rangle\} \cup S, D' \rangle \end{array}$$

$$\begin{array}{c} \text{(S-DEPLOY-EXISTING)} \\ \Sigma = \mathcal{E}[\mathcal{S}_{DEP}\langle t_b, C\langle t_c, N, \Sigma_c \rangle, \bar{\sigma} \rangle] \quad i'_d = D(t_b, t_c) \quad \Sigma' = \mathcal{E}[i'_d] \\ \mathcal{K}\langle E, I_d, W, \{\mathcal{S}\langle t_d, \Sigma \rangle\} \cup S, D \rangle \\ \rightarrow_k \mathcal{K}\langle E, \{i'_d\} \cup I_d, W, \{\mathcal{S}\langle t_d, \Sigma' \rangle\} \cup S, D \rangle \end{array}$$

Inter-Turn Semantics (Driver Loop)

Semantic Entities:
 $k^{inter} \in \text{Inter-Turn Configuration} ::= \mathcal{K}^{inter} \langle \tau, k \rangle$
 $\tau \subseteq \text{Primitive Time-Varying Sources} ::= \{x \mapsto \bar{v}, \dots\}$
 $\tilde{k} \in \tilde{K} \subset K$ where $\tilde{k} \not\vdash_k$

• Perform intra-turn steps “forever”

Initial Configuration
 $k_{init}^{inter} = \mathcal{K}^{inter} \langle \tau_{init}, k_{init} \rangle$
 $\tau_{init} = \{time \mapsto \dots\}$
Reduction Rule
 (INTRA-TURN)
 $k \vdash \dots$
 $\mathcal{K}^{inter} \langle \tau, k \rangle \vdash \dots$

(NEXT-TURN)

$$\frac{\begin{array}{l} k = \mathcal{K} \langle E, I_d, W, S, D \rangle \in \tilde{K} \\ S \langle \iota_{main,d}, E_{main} \rangle \in S \\ k' = \mathcal{K} \langle E[x_i \mapsto v_{i,now} \mid \forall i \in [1..|\tau|]], \{ \iota_{main,d} \}, W, \emptyset, D \rangle \end{array}}{\mathcal{K}^{inter} \langle \{x_i \mapsto [v_{i,now}] \S \bar{v}_i \mid \forall i \in [1..|\tau|] \rangle, k \rangle \rightsquigarrow \mathcal{K}^{inter} \langle \{x_i \mapsto \bar{v}_i \mid \forall i \in [1..|\tau|] \rangle, k' \rangle}$$

each turn
 eter...

r loop of the

(NEXT-TURN)

$$\frac{\begin{array}{l} k = \mathcal{K} \langle E, I_d, W, S, D \rangle \in \tilde{K} \\ S \langle \iota_{main,d}, E_{main} \rangle \in S \\ k' = \mathcal{K} \langle E[x_i \mapsto v_{i,now} \mid \forall i \in [1..|\tau|]], \{ \iota_{main,d} \}, W, \emptyset, D \rangle \end{array}}{\mathcal{K}^{inter} \langle \{x_i \mapsto [v_{i,now}] \S \bar{v}_i \mid \forall i \in [1..|\tau|] \rangle, k \rangle \rightsquigarrow \mathcal{K}^{inter} \langle \{x_i \mapsto \bar{v}_i \mid \forall i \in [1..|\tau|] \rangle, k' \rangle}$$

- **Motivation**

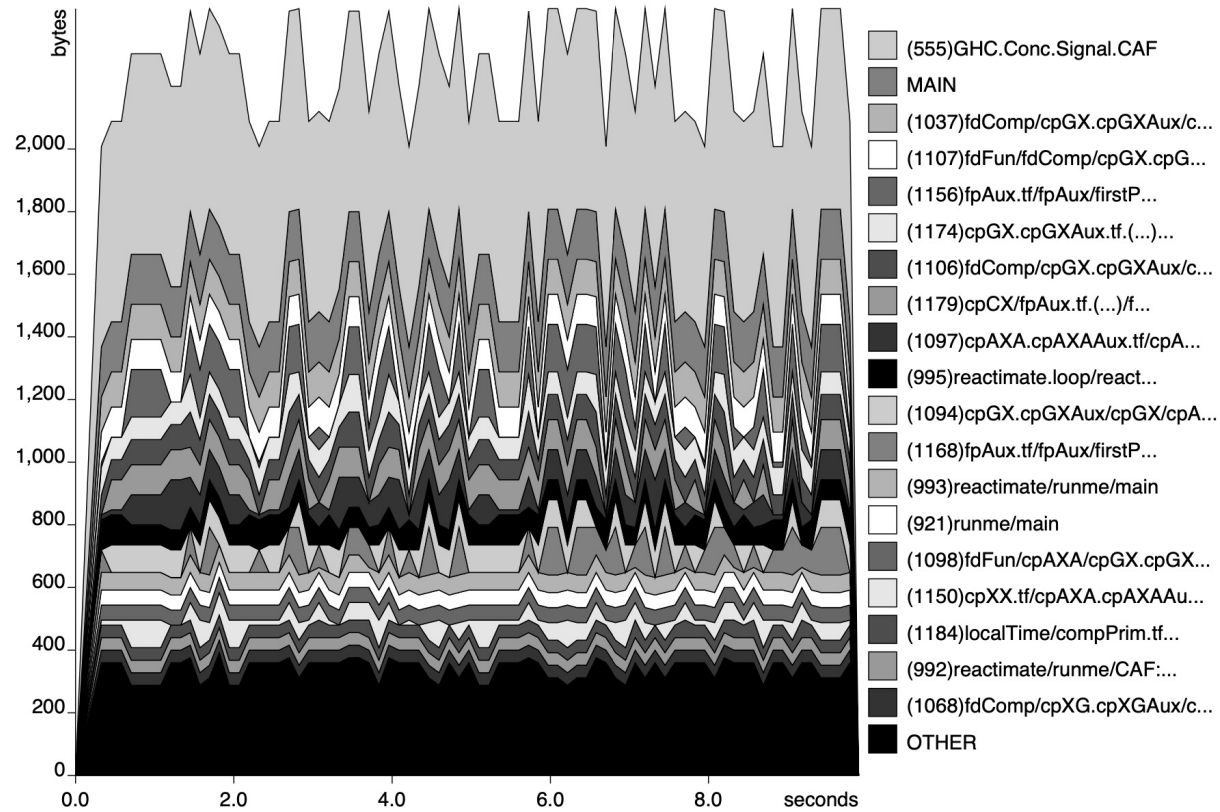
- **Formalisation**

- **Lessons learned**

Lessons Learned

- Graph-based RP needs wiring and propagation
 - w-rules and s-rules
 - Wiring and propagating can, in general, be interleaved!
 - Run-time wiring decisions due to higher-order reactivity
- Memory consumption ...

Remember this graph?



Why does this happen?

(>>>): sequential composition of SFs

Signal Functions

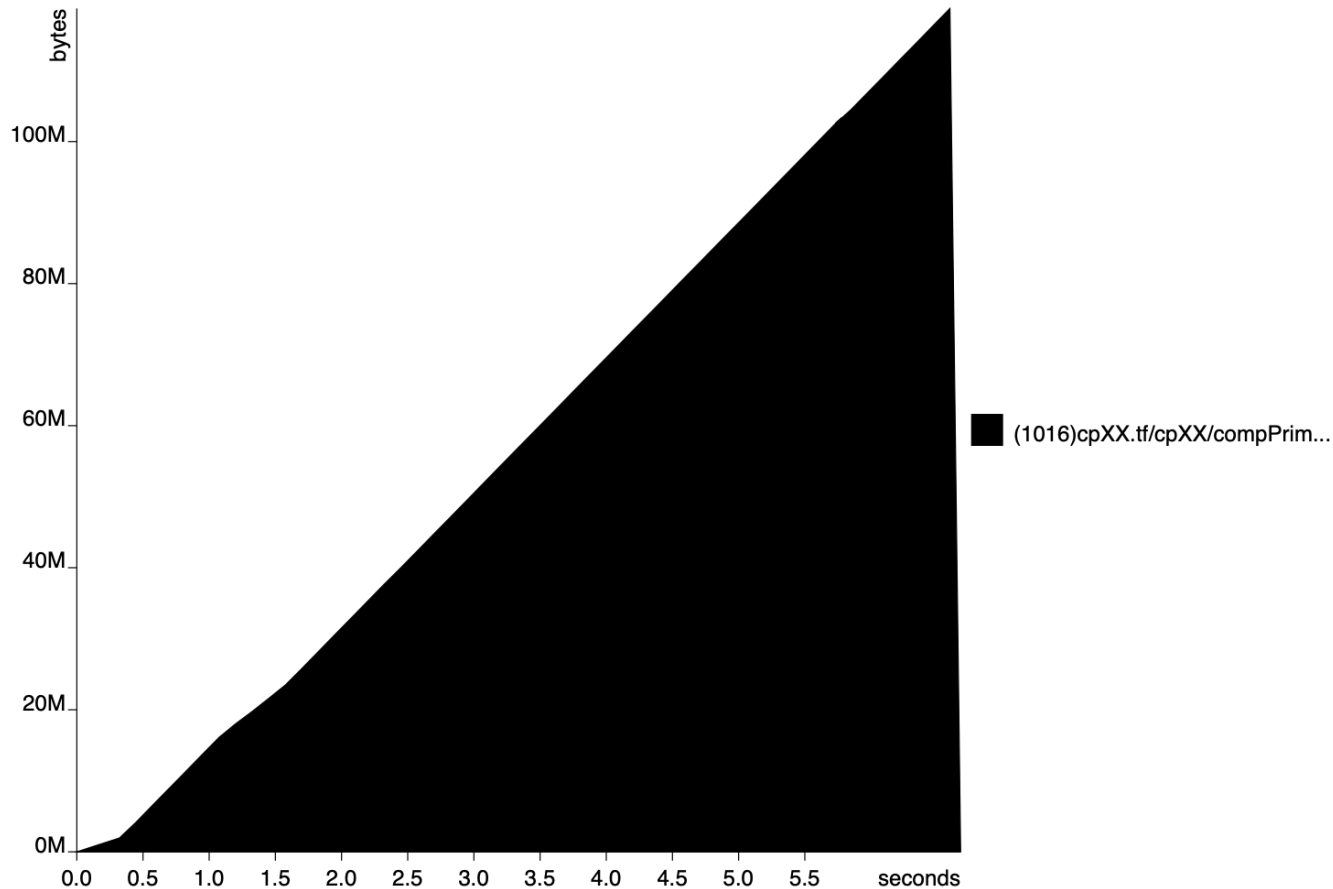
```
(>>>) :: SF a b -> SF b c -> SF a c
(SF {sfTF = tf1}) >>> (SF {sfTF = tf2}) =
  SF {sfTF = tf}
  where
    tf dt a = (sf1' >>> sf2', c)
      where
        (sf2', c) = tf2 dt b
        (sf1', b) = tf1 dt a
```

Recursion

Elegant, because it's all *just* composition of functions.

Actually, this is not what really happens due to optimisations...

Without optimisations



GC isn't possible!

Each recursive application of (\gg) extends the function's lexical environment. In addition to Haskell's lazy evaluation model, this introduces a space leak!

Which is what graph-based RPLs avoid altogether by treating RP programs as graphs [*].

In case of Karcharias...

(NEXT-TURN)

$$k = \mathcal{K}\langle E, I_d, W, S, D \rangle \in \tilde{K}$$

$$S\langle \iota_{main,d}, E_{main} \rangle \in S$$

$$k' = \mathcal{K}\langle E[x_i \mapsto v_{i,now} \mid \forall i \in [1..|\tau|]], \{\iota_{main,d}\}, W, \emptyset, D \rangle$$

$$\frac{}{\mathcal{K}^{inter}\langle \{x_i \mapsto [v_{i,now}] \S \bar{v}_i \mid \forall i \in [1..|\tau|]\}, k \rangle}$$
$$\rightsquigarrow \mathcal{K}^{inter}\langle \{x_i \mapsto \bar{v}_i \mid \forall i \in [1..|\tau|]\}, k' \rangle$$

- Easy/ier to determine memory consumption
 - Wirings remain static, after they have been constructed.
 - Snapshots are "reduced" versions of wirings (with actual values of signals)

Question now becomes: when do we have to wire?

Future Work

- Currently lacking:
 - No error handling / detection of stuck states
 - Stateful computations aren't formalised yet
 - Thorough comparison between function-based RP and graph-based RP
- Ultimate goal
 - Expressive, higher-order, RP language that works for very small computers
 - Statically classify RP programs w.r.t. their required memory allocation/consumption behaviour

Looking for ideas!



A Graph-Based Formal Semantics of Reactive Programming from First Principles

Bjarno Oeyen, Joeri De Koster, Wolfgang De Meuter

Software Languages Lab, Vrije Universiteit Brussel, Belgium

FTfJP Workshop @ Ecoop (07/06/2022)